

LESSON PLAN (SUMMER-2023)

Discipline: ETC	Semester:6th	Name of the Teaching Faculty: SOMA DASH
Subject: Digital Signal Processing	No of Days /per week class allotted: 4	Semester From date: 14.02.2023 To date: 23.05.2023 No of Weeks:14
Week	Class Day	Theory / Practical Topics
1st	1st	1. Introduction of Signals, Systems & Signal processing(10) 1.1 Basics of Signals, Systems & Signal processing- basic element of a digital signal processing system -
	2nd	Compare the advantages of digital signal processing over analog signal processing.
	3rd	1.2 Classify signals - Multi channel& Multi-dimensional signals-Continuous time verses Discrete -times Signal. -
	4th	Continuous valued verses Discrete -valued signals.
2nd	1st	1.3 Concept of frequency in continuous time & discrete time signals- Continuous-time sinusoidal signals-Discrete-time sinusoidal signals- Harmonically related complex exponential.
	2nd	1.4 Analog to Digital & Digital to Analog conversion & explain the following. a. Sampling of Analog signal,
	3rd	b. The sampling theorem.
	4th	c. Quantization of continuous amplitude signals, d. Coding of quantized sample.
3rd	1st	e. Digital to analog conversion.
	2nd	f. Analysis of digital systems signals vs. discrete time signals systems.
	3rd	2. DISCRETE TIME SIGNALS & SYSTEMS (14) 2.1 Concept of Discrete time signals. 2.1.1 Elementary Discrete time signals. 2.1.2 Classification Discrete time signal.
	4th	2.1.3 Simple manipulation of discrete time signal.
4th	1st	2.2 Discrete time system. 2.2.1 Input-output of system.
	2nd	2.2.2 Block diagram of discrete- time systems
	3rd	2.2.3 Classify discrete time system.
	4th	2.2.4 Inter connection of discrete -time system.
5th	1st	2.3 Discrete time time-invariant system. 2.3.1 Different techniques for the Analysis of linear system.
	2nd	2.3.2 Resolution of a discrete time signal in to impulse.
	3rd	2.3.3 Response of LTI system to arbitrary inputs using convolution sum.
	4th	2.3.4 Convolution & interconnection of LTI system - properties.
6th	1st	2.3.5 Study systems with finite duration and infinite duration impulse response.
	2nd	2.4 Discrete time system described by difference equation. 2.4.1 Recursive & non-recursive discrete time system.
	3rd	2.4.2 Determine the impulse response of linear time invariant recursive system.
	4th	2.4.3 Correlation of Discrete Time signals

7th	1st	3. THE Z-TRANSFORM & ITS APPLICATION TO THE ANALYSIS OF LTI SYSTEM. (14)
	2nd	3.1 Z-transform & its application to LTI system.
	3rd	3.1.1 Direct Z-transform.
	4th	3.1.2 Inverse Z-transform.
8th	1st	3.2 Various properties of Z-transform.
	2nd	Continue
	3rd	3.3 Rational Z-transform.
	4th	3.3.1 Poles & zeros.
9th	1st	3.3.2 Pole location time domain behaviour for casual signals.
	2nd	3.3.3 System function of a linear time invariant system.
	3rd	3.4 Discuss inverse Z-transform.
	4th	3.4.1 Inverse Z-transform by partial fraction expansion.
10th	1st	Continue
	2nd	3.4.2 Inverse Z-transform by contour Integration
	3rd	Continue
	4th	4. DISCUSS FOURIER TRANSFORM: ITS APPLICATIONS PROPERTIES(12)
11th	1st	4.1 Concept of discrete Fourier transform.
	2nd	4.2 Frequency domain sampling and reconstruction of discrete time signals.
	3rd	4.3 Discrete Time Fourier transformation(DTFT)
	4th	Continue
12th	1st	4.4 Discrete Fourier transformation (DFT).
	2nd	Continue
	3rd	4.5 Compute DFT as a linear transformation.
	4th	4.6 Relate DFT to other transforms.
13th	1st	4.7 Property of the DFT.
	2nd	4.8 Multiplication of two DFT & circular convolution
	3rd	5. FAST FOURIER TRANSFORM ALGORITHM & DIGITAL FILTERS(10)
	4th	5.1 Compute DFT & FFT algorithm.
14th	1st	Continue
	2nd	5.2 Direct computation of DFT.
	3rd	5.3 Divide and Conquer Approach to computation of DFT
	4th	5.4 Radix-2 algorithm. (Small Problems)
15th	1st	5.5 Application of FFT algorithms
	2nd	5.6 Introduction to digital filters.
	3rd	(FIR Filters)& General considerations
	4th	5.7 Introduction to DSP architecture, familiarisation of different types of processor

Signature of the Faculty